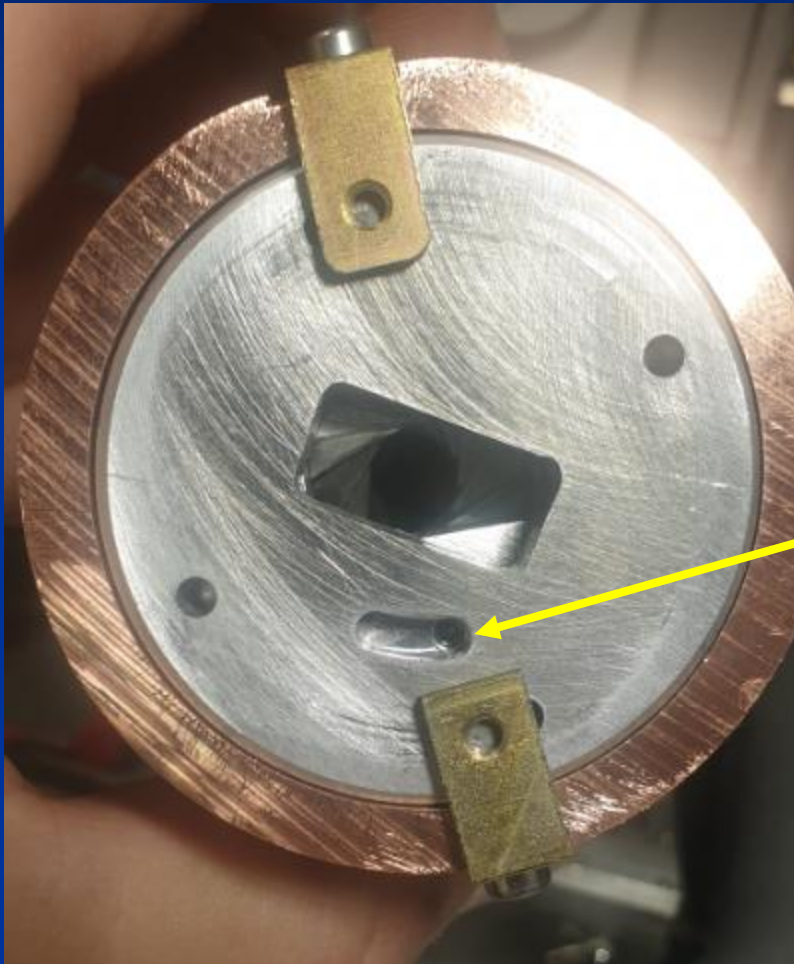


Practical realization of the 10 GHz Polarizer



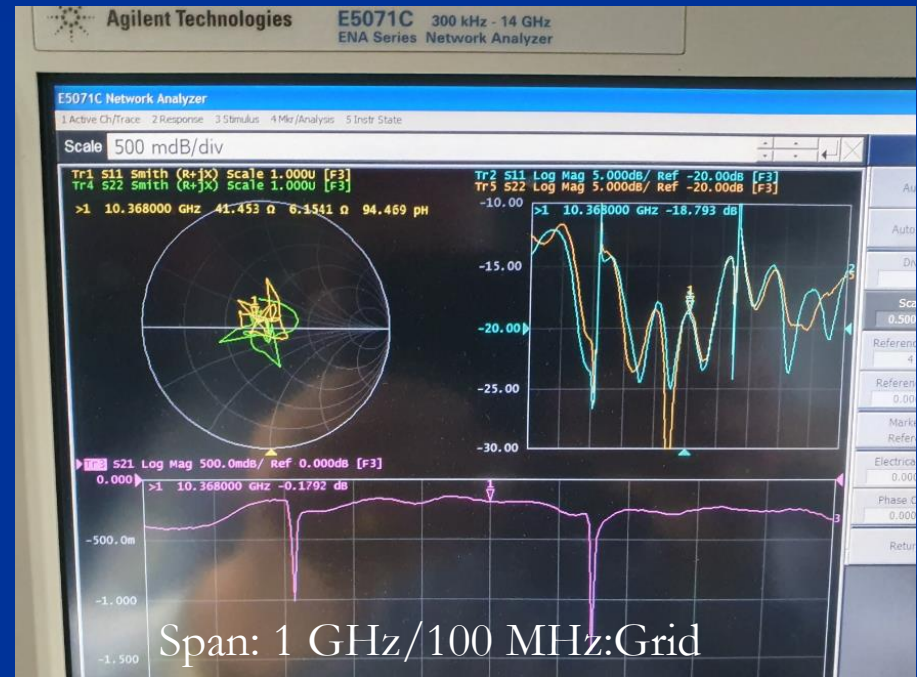
It may look good – however the results were poor...

Driver screw, 25 deg. per disc

Practical realization of the 10 GHz Polarizer



WR-75 flange (prior to solder WG)

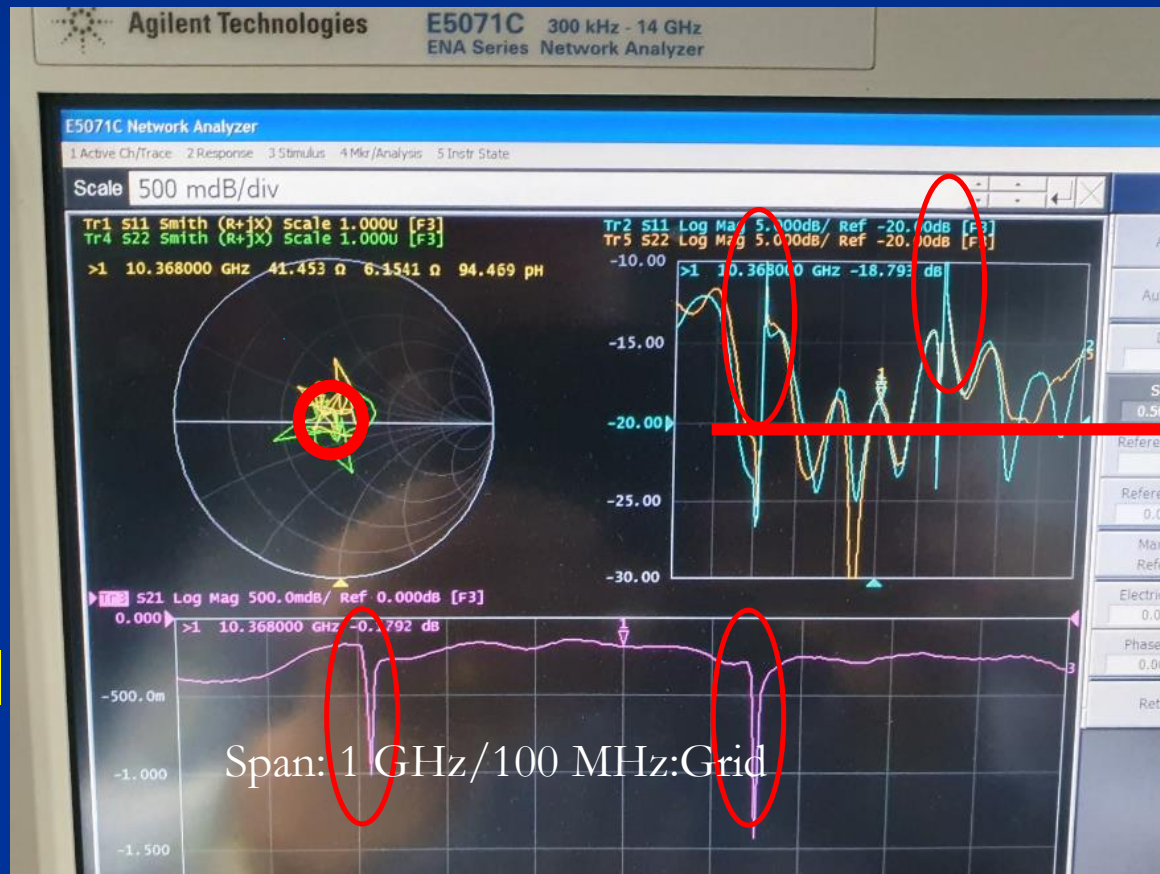




Practical realization of the 10 GHz Polarizer



Very bad match, extremely narrow band, unacceptable insertion loss **Failed!**



S12 failed

S11 - 20 dB failed

Advise needed!



Second attempt: A truly seasoned microwave professional:

**René, HB9MPU (@ time 88) (now 91)
(former head of final testlab @ STR)**



All edges inside a WG create diffusion of the RF and deflection from the straight path.

This creates different path-lengths and thus phase errors

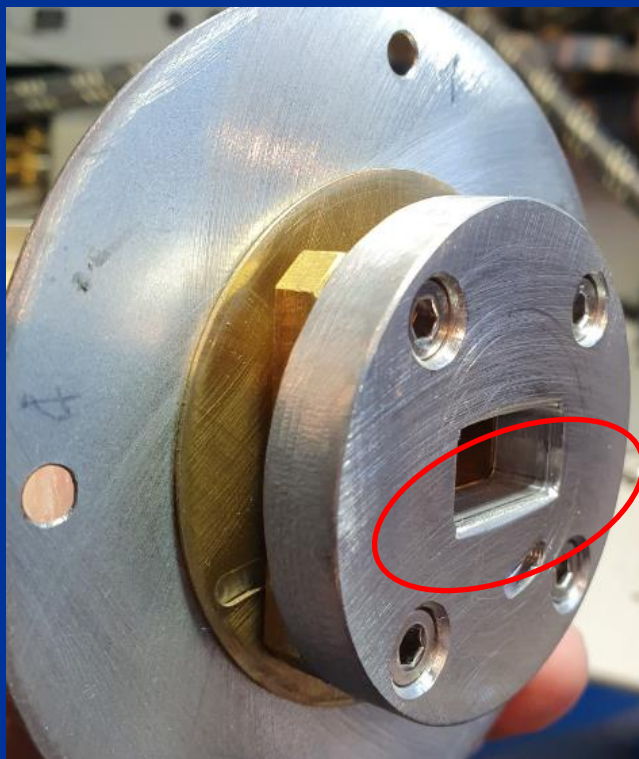
These corrupt a good match, and cannot be corrected. The result is a wild up-and-down of return loss which obviously impacts the insertion loss.

The long edges inside the WG have to be rounded



Practical realization of the 10 GHz Polarizer

The long edges inside the WG have to be rounded

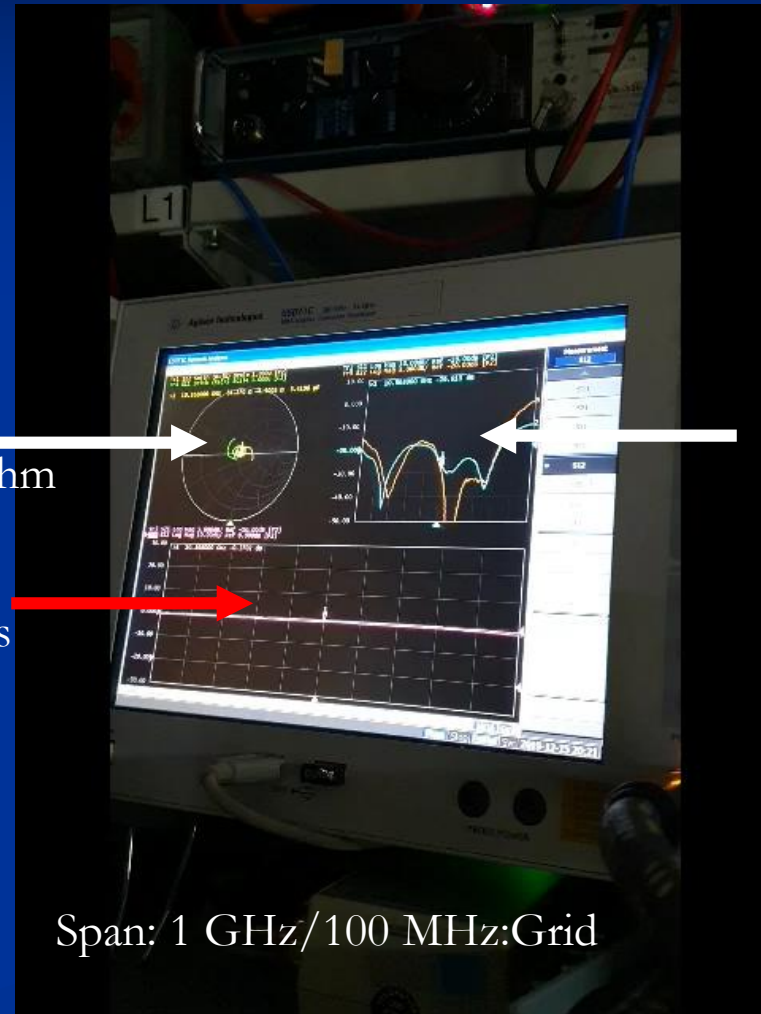


Practical realization of the 10 GHz Polarizer



S11, S22
Impedance
approx. 50 Ohm

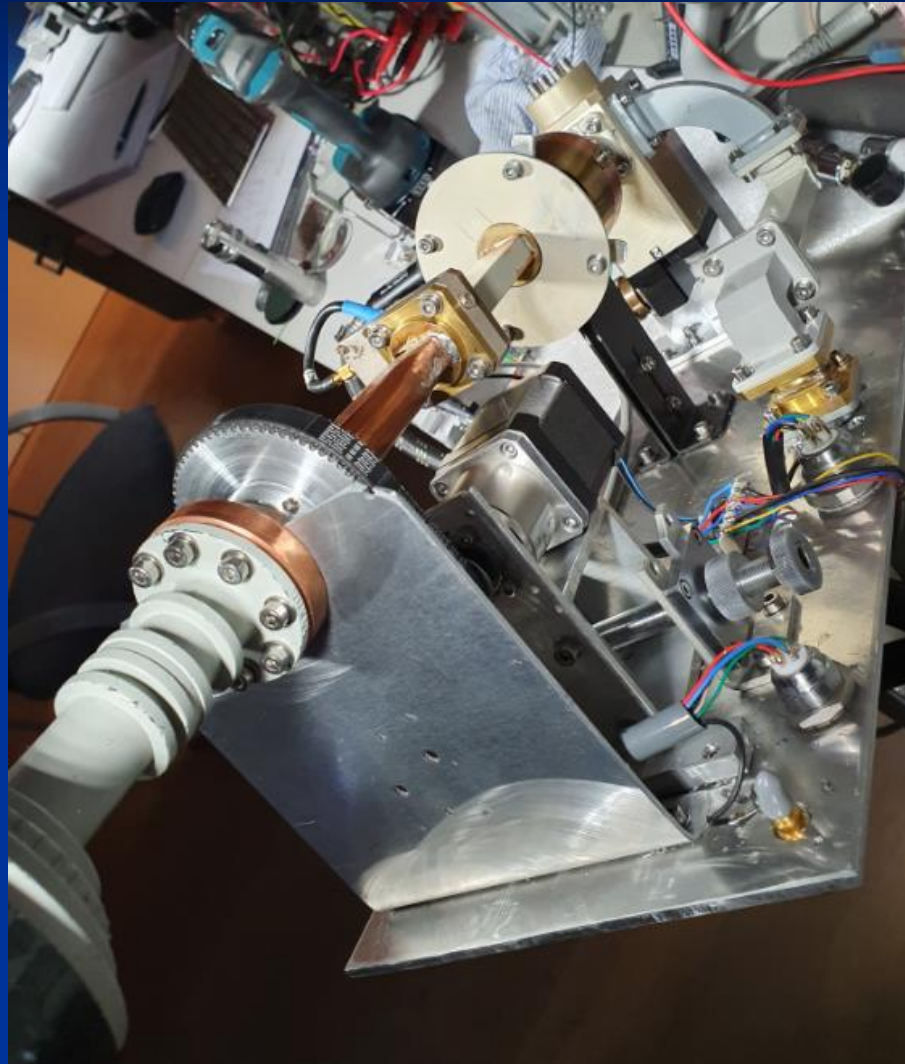
S12, S21
Insertion loss
 ≤ 0.3 dB



S11, S22
Return loss
 ≥ -20 dB

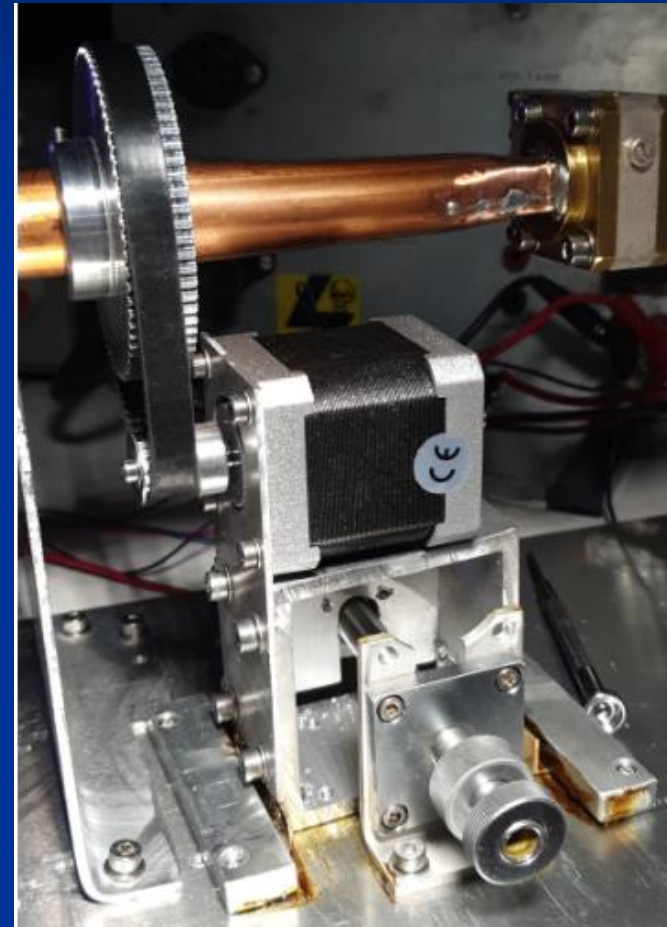
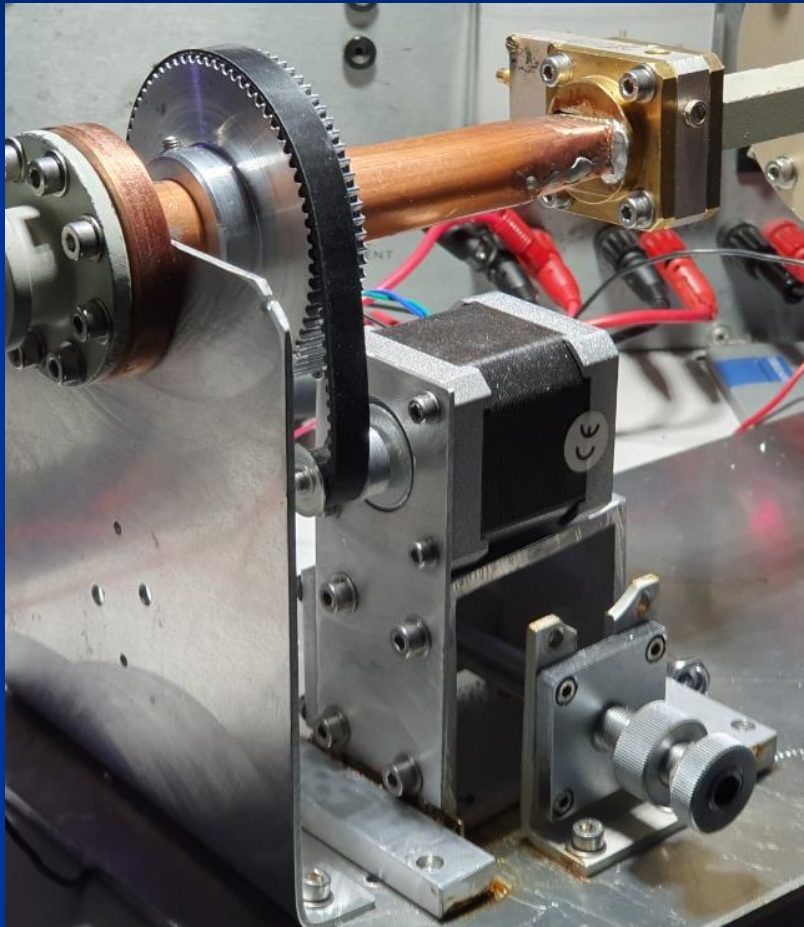
Span: 1 GHz/100 MHz:Grid

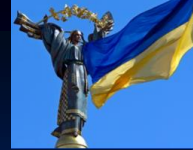
Feed unit for offset dish





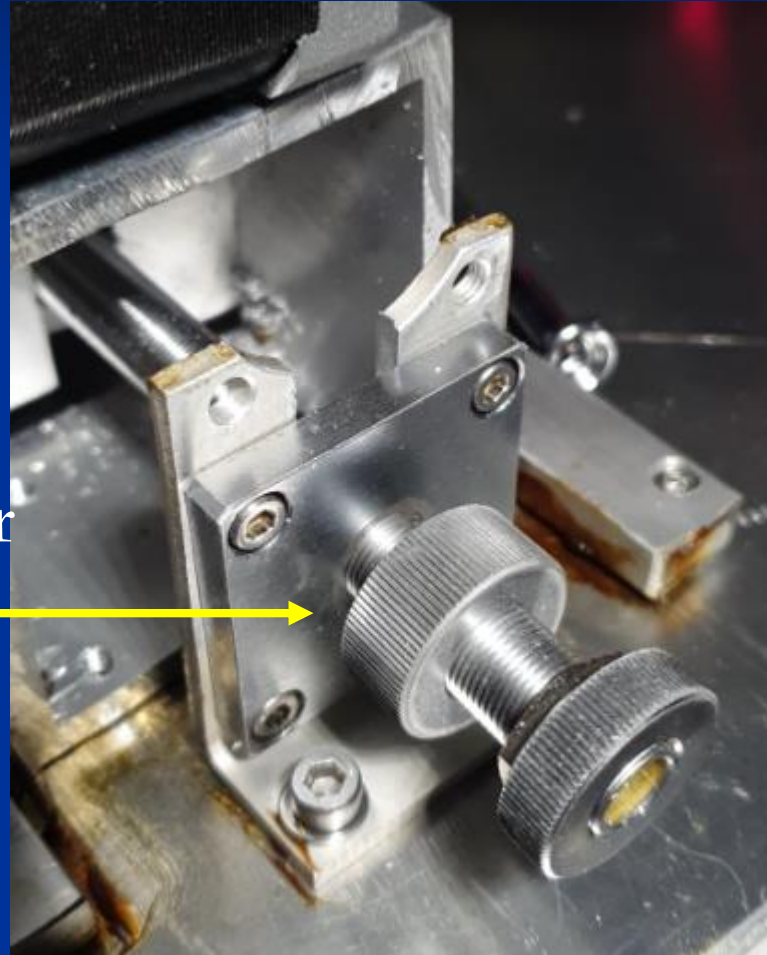
StepMotor, Control and display of Polarization angle



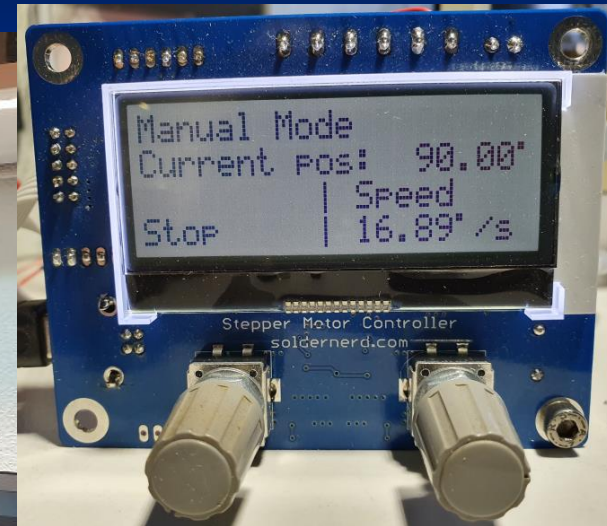
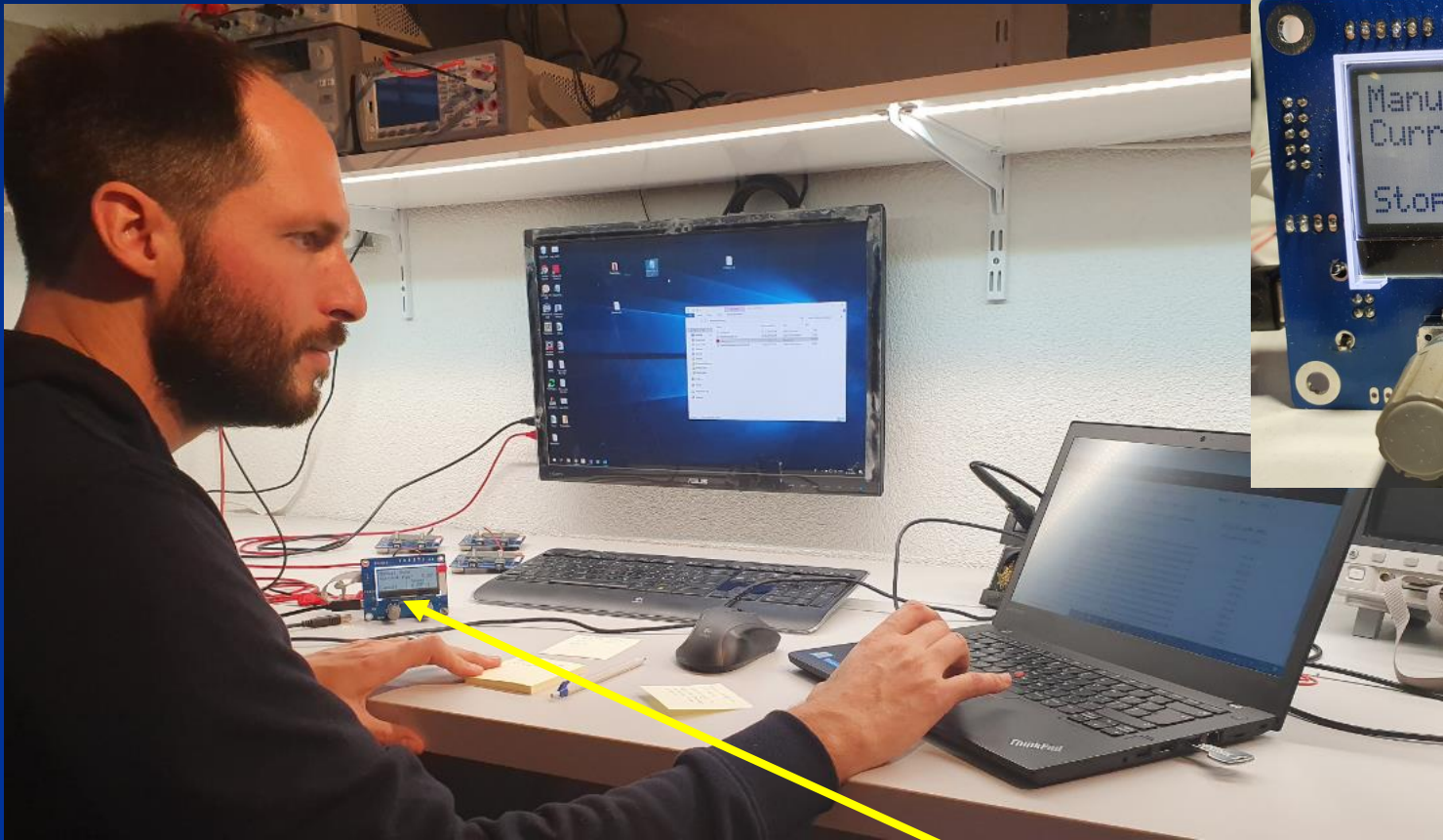


StepMotor, belt adjustment

Precision thread of an
obsolete UHF band-pass filter



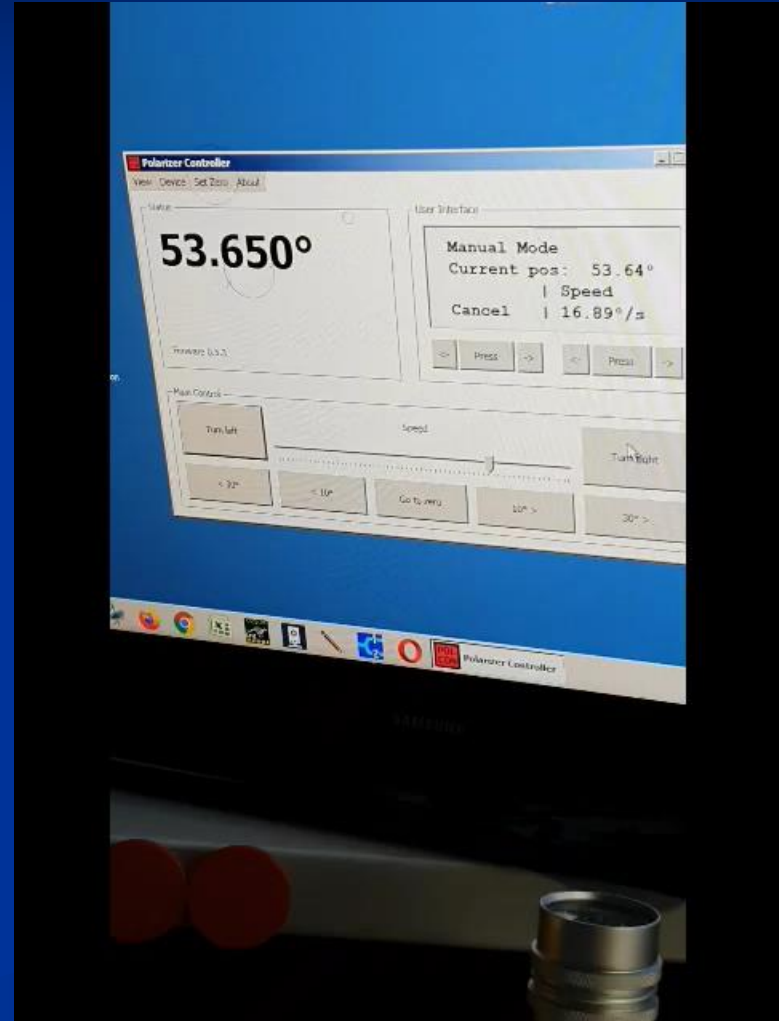
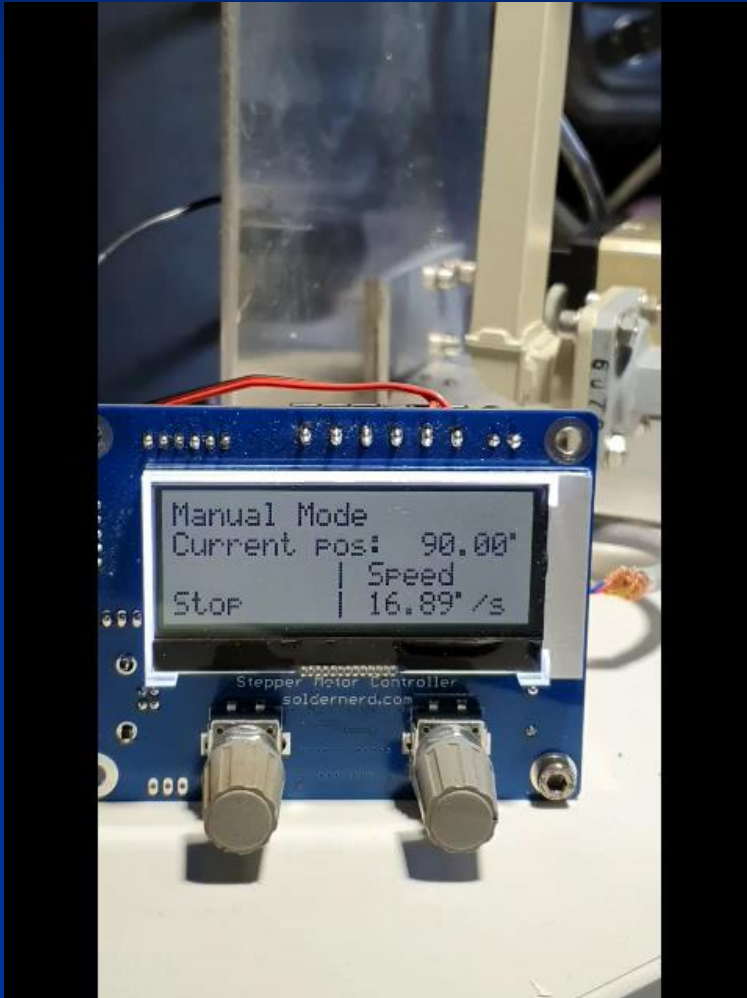
StepMotor, Control and display of Polarization angle



Lukas Fässler, HB9TKO. He developed the Control unit



StepMotor, Control and display of Polarization angle

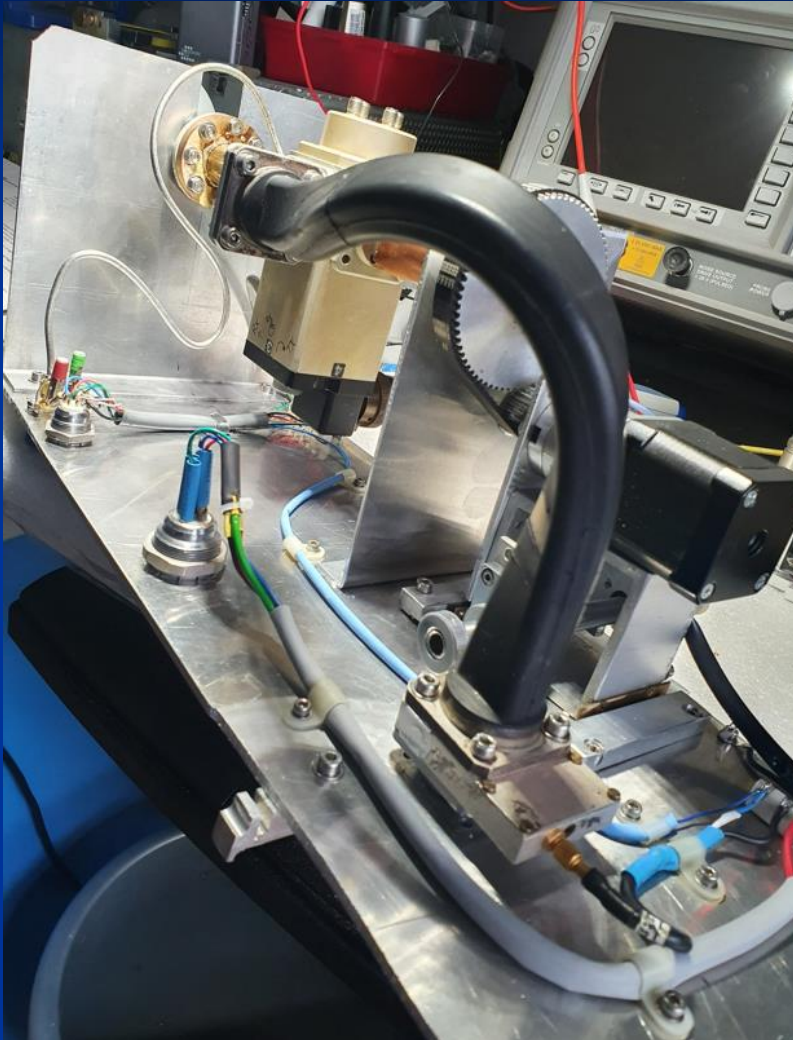


Conclusions



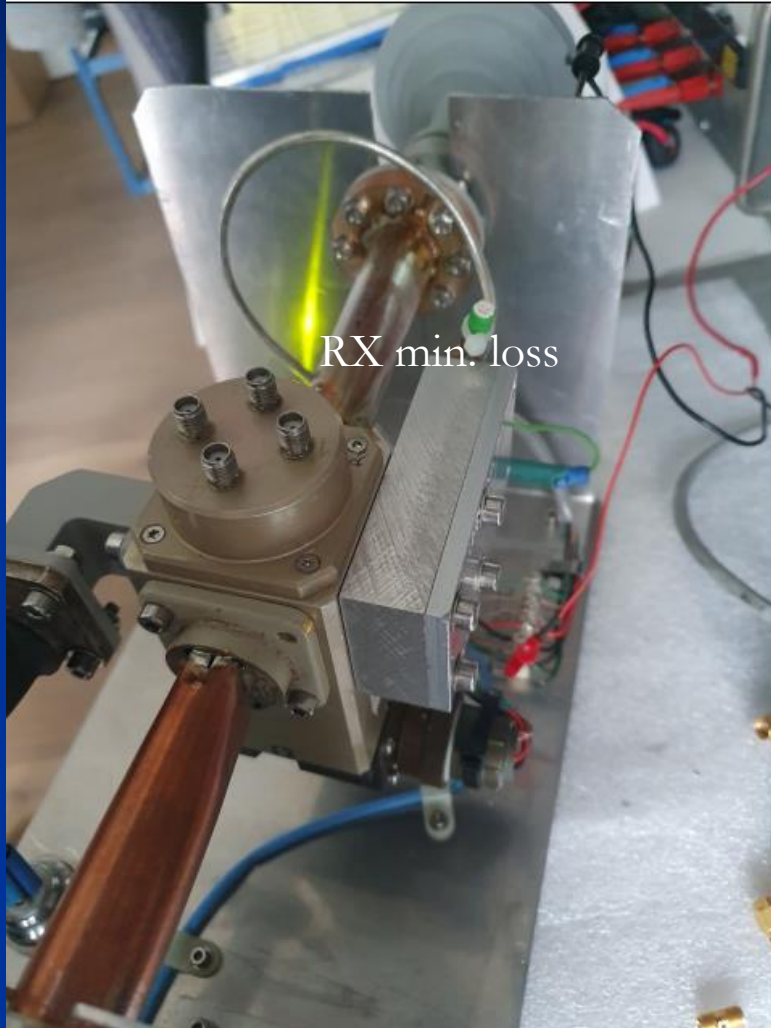
- The mechanical polarizer failed to satisfy
- The loss in RX mode was unacceptable by 0,3dB
- Major issue was limited RX-performance
- *There must be a more efficient way of rotatable lin. polarization*

New Attempt



- Rotating WG Switch
incl. LNA
- «bend&twist»
flexible TX-line
- Same control
HW/SW

New Attempt



RX min. loss



TX acceptable loss

References



StepperController Desktop Software:

- ❖ <https://github.com/soldernerd/RotaryTableApp>
lfaessler(at)gmail.net

Populated with Display Euro 125 + postage

Motor driver:

- ❖ <https://planet-cnc.com/product/motordriver-6-0a-256/>



*XVII International EME Conference – Venice 2016 Conference Proceedings 97
G3WDG –*

- ❖ *Experiences with Circular Polarisation on 10GHz Charlie Suckling (e-mail:
charlie@sucklingfamily.free-online.co.uk)*

Questions? Observations?

